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Improvement of MC Method in SAE J2601 Hydrogen Refuelling Protocol Using Dual-Zone Dual-Temperature Model

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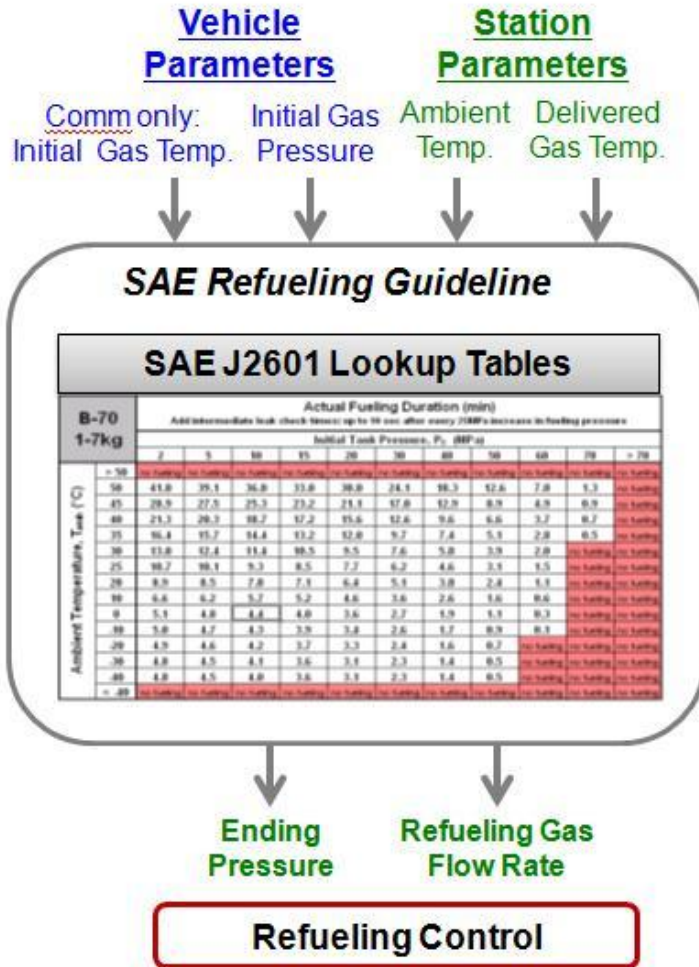
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Introduction

Inputs



Station Dispenser Type

- T40 Station H2@ -40 °C
- T30 Station H2@ -30 °C
- T20- Station H2@ -20 °C

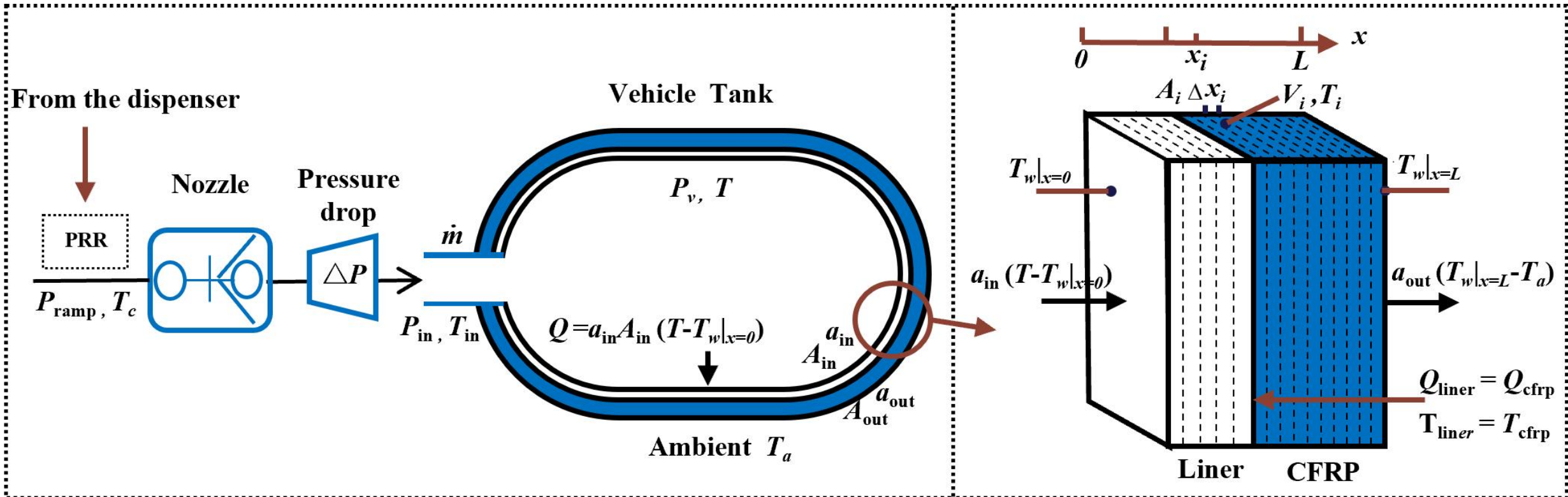
[*]<https://www.sae.org/news/2014/07/hydrogen-fueling-protocol-spelled-out-in-new-sae-international-j2601-standard>

- In order to refuel hydrogen fuel cell vehicles quickly and safely, two **refueling methods** have been implemented in SAE J2601, include **lookup table method** and **MC method**.
- Both methods control the **refueling gas flow rate** and **ending pressure** according to the **vehicle parameters** and **station parameters**.
- **Refueling gas flow rate** is reflected by pressure ramp rate (**PRR**).
- This article mainly improves the **calculation method of the ending pressure** in MC method. Accurate estimation for final hydrogen temperature, ending pressure and final SOC to control the refuelling is **safer**.

Model Description

0D1D hydrogen filling model

- This Figure shows a **simplified hydrogen filling model** from the dispenser to the vehicle tank.
- **Hydrogen** inside tank is lumped parameter model (**0D**), and tank wall is represented by one-dimensional model (**1D**).
- This 0D1D model is used to **generate simulation data to fit the correction factor** and **verify the modified MC method**.



Model Description

Mathematical equations for 0D1D model

- Mass and energy conservation for hydrogen inside tank

$$\frac{dm}{dt} = \dot{m}_{\text{in}} - \dot{m}_{\text{out}}$$

$$\frac{d(mu)}{dt} = \dot{m}_{\text{in}} h_{\text{in}} - \dot{m}_{\text{out}} h_{\text{out}} + \dot{Q}$$

- Heat transfer equation for one-dimensional tank wall

$$\lambda_w \frac{\partial^2 T_w}{\partial x^2} = \rho_w c_w \frac{\partial T_w}{\partial t}$$

- Boundary conditions of inner and outer surfaces of tank

$$-\lambda_w \left. \frac{\partial T_w}{\partial x} \right|_{x=0} = \alpha_{\text{in}} (T - T_w|_{x=0})$$

$$-\lambda_w \left. \frac{\partial T_w}{\partial x} \right|_{x=L} = \alpha_{\text{out}} (T_w|_{x=L} - T_a)$$

- Heat transfer coefficient between hydrogen and inner wall

$$\alpha_{\text{in}} = \frac{0.14 \lambda \text{Re}_{d_{\text{in}}}^{0.67}}{D_{\text{in}}}$$

- Heat transfer coefficient between outer wall and ambient

$$\alpha_{\text{out}} = \frac{\lambda_a \text{Pr}_a^{0.4} \left(0.4 \text{Re}_{D_{\text{out}}}^{0.5} + 0.06 \text{Re}_{D_{\text{out}}}^{2/3} \right)}{D_{\text{out}}}$$

- Pressure drop

$$\Delta P = k_p \frac{\dot{m}^2}{\rho}$$

Model Description

Control process of MC method—Refueling gas flow rate \Rightarrow reflected by the pressure ramp rate (**PRR**).

- Calculate **mass average temperature (MAT)** of the inlet flow.
- Calculate the MAT for control (**MATC**) based on three rules.
- Calculate final filling time t_{final} using MATC.
- Calculate **PRR** using t_{final} .

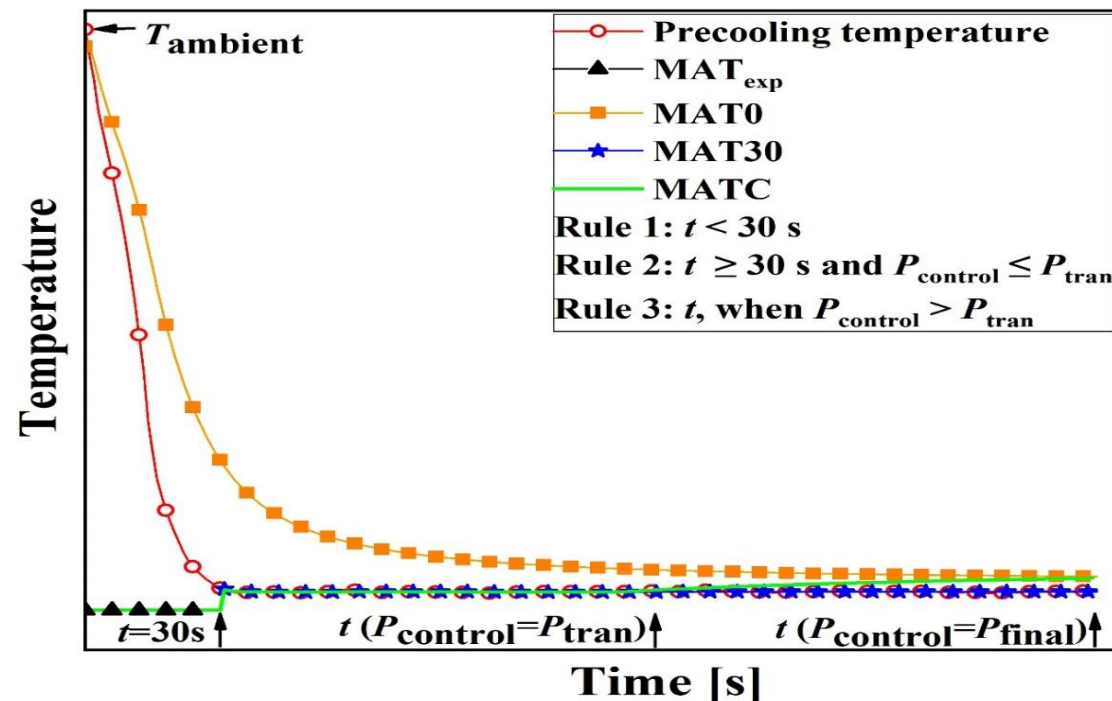
$$\text{MAT}_{(j)} = \frac{\sum_1^j (m_{(j)} - m_{(j-1)}) \times 0.5(T_{(j)} + T_{(j-1)})}{\sum_1^j (m_{(j)} - m_{(j-1)})}$$

(1) Rule 1: if $t(j) \leq 30$ s, $\text{MATC}_{(j)} = \text{MAT}_{\text{exp}}$

(2) Rule 2: if $t(j) > 30$ s and $P_{\text{control}(j)} \leq P_{\text{trans}}$, $\text{MATC}_{(j)} = \text{MAT30}_{(j)}$

(3) Rule 3: if $P_{\text{control}(j)} > P_{\text{trans}}$,

$$\text{MATC}_{(j)} = \text{MAT30}_{(j)} \left(\frac{P_{\text{final}} - P_{\text{control}(j)}}{P_{\text{final}} - P_{\text{trans}}} \right) + \text{MAT0}_{(j)} \left(1 - \frac{P_{\text{final}} - P_{\text{control}(j)}}{P_{\text{final}} - P_{\text{trans}}} \right)$$



$$t_{\text{final}(j)} = a \times \text{MATC}_{(j)}^3 + b \times \text{MATC}_{(j)}^2 + c \times \text{MATC}_{(j)} + d$$

$$\text{PRR}_{(j)} = \frac{P_{\text{final}} - P_{\text{ramp}(j)}}{t_{\text{final}(j)} \left(\frac{P_{\text{final}} - P_{\text{initial}}}{P_{\text{final}} - P_{\text{min}}} \right) - t(j)}$$

Model Description

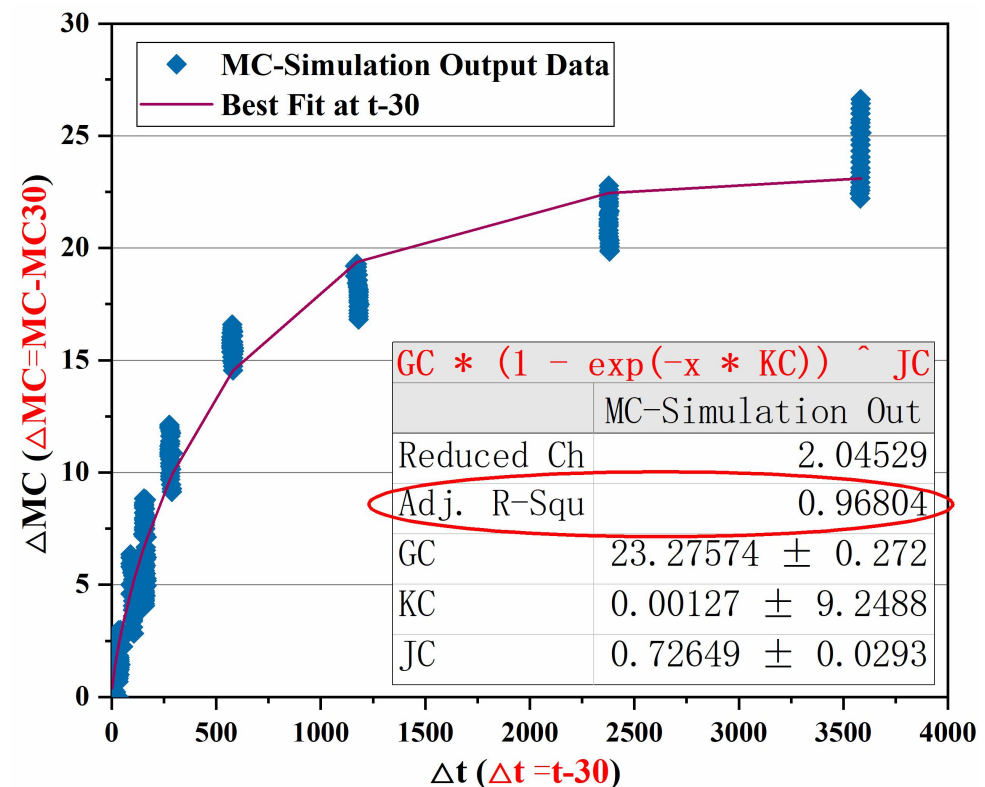
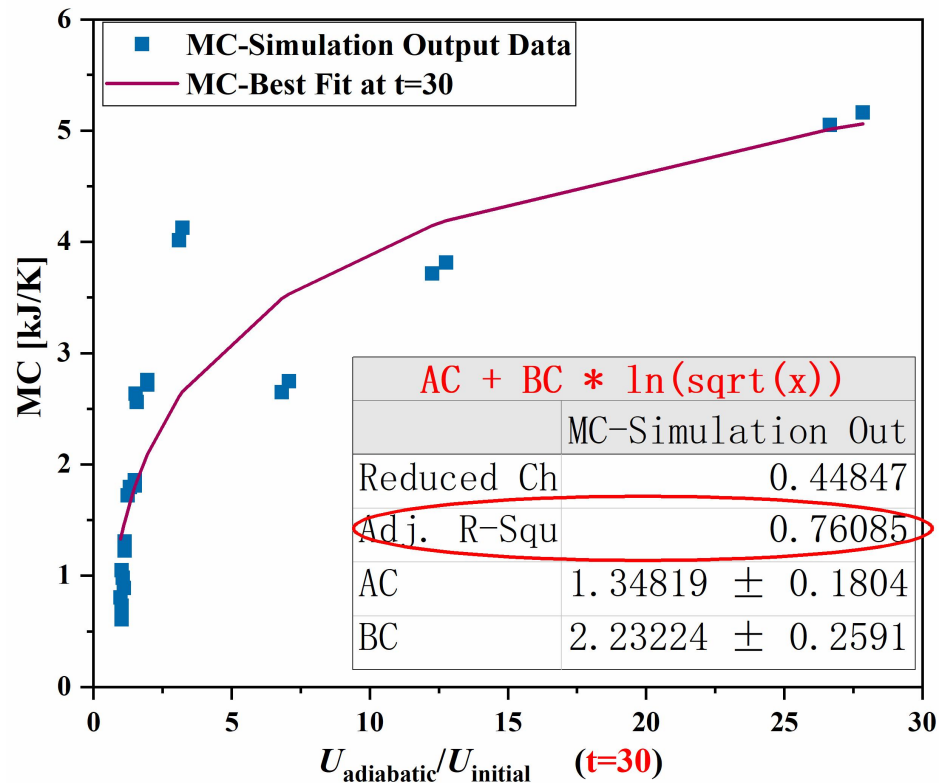
Control process of MC method—Ending Pressure

- The analytical solution of final hydrogen temperature is used to determine ending pressure (target pressure).
- Data from 0D1D model are used to fit the MC expression.
- Left figure is the result of fitting the first term.
- Right figure is the result of fitting the second term.

$$T_{\text{final}} = \frac{m_{\text{final}}c_v T_{\text{adiabatic}} + \text{MC}T_{\text{initial}}}{\text{MC} + m_{\text{final}}c_v}$$

$$P_{\text{target}} = f(T_{\text{final}}, \text{SOC}_{\text{target}})$$

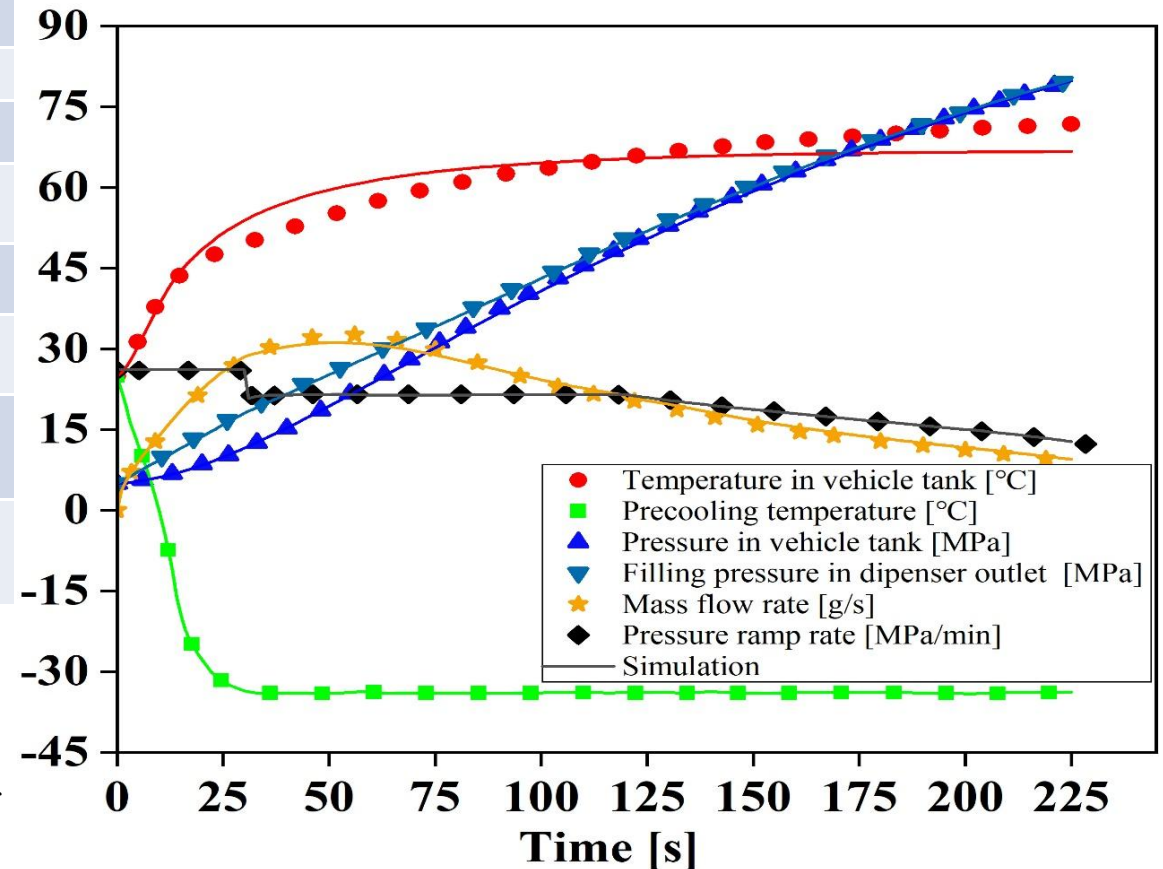
$$\text{MC} = \text{AC} + \text{BC} \ln \left(\frac{U_{\text{adiabatic}}}{U_{\text{initial}}} \right)^{1/2} + \text{GC} (1 - e^{-\text{KC}\Delta t})^{\text{JC}}$$



Model Validation

| | | Model validation | Improvements for MC method | |
|------------|-----------------------------------|-----------------------|----------------------------|-----------|
| | Units | 70 MPa Type IV [3] | 1kg 70 MPa Type III [1] | |
| Geometry | Internal gas volume | liter | 129 | 25 |
| | Total external length | mm | 722 | 835 |
| | Internal liner surface area | m ² | 1.3 | 0.5 |
| | External/Internal diameter | mm | 600/513 | 240/200 |
| | Liner/CFRP wall thickness | mm | 5/38.3 | 3.25/16.7 |
| | Liner/CFRP mass | kg | 6.1/72.4 | 4.7/14.9 |
| Properties | Liner/CFRP density | kg/m ³ | 975/1550 | 2700/1494 |
| | Liner/CFRP thermal conductivity | W/m/K | 0.3/0.3 | 164/0.74 |
| | Liner/CFRP specific heat capacity | J/kg/K | 1000/500 | 1106/1120 |

- These model parameters are shown in the left table.
- PRR (black diamond) changes dynamically in three stages according to the three rules.
- The hydrogen mass flow rate (yellow star) agrees very well.
- The pressure (blue triangle) and temperature (red circle) of hydrogen agree well.



[1] Society of Automotive Engineers (SAE)., SAE J2601 (2020): Fueling protocols for light duty gaseous hydrogen surface vehicles, https://www.sae.org/standards/content/j2601_202005/.

[3] Reddi, K. and Elgowainy, A., Impact of hydrogen SAE J2601 fueling methods on fueling time of light-duty fuel cell electric vehicles, Int J Hydrogen Energy, 42, No. 26, 2017, pp. 16675-16685.

Improvements for MC method

Ending pressure determined by **dual-zone single-temperature** model in original MC method

Thermodynamic energy conservation during a refueling time of $t_{\text{initial}} - t_{\text{final}}$:

Hydrogen energy is transferred to the tank wall
(assuming that the outer wall of the tank is **adiabatic**):
 $m_{\text{final}}c_v(T_{\text{adiabatic}} - T_{\text{final}}) = MC(T_{\text{wfinal}} - T_{\text{initial}})$

+

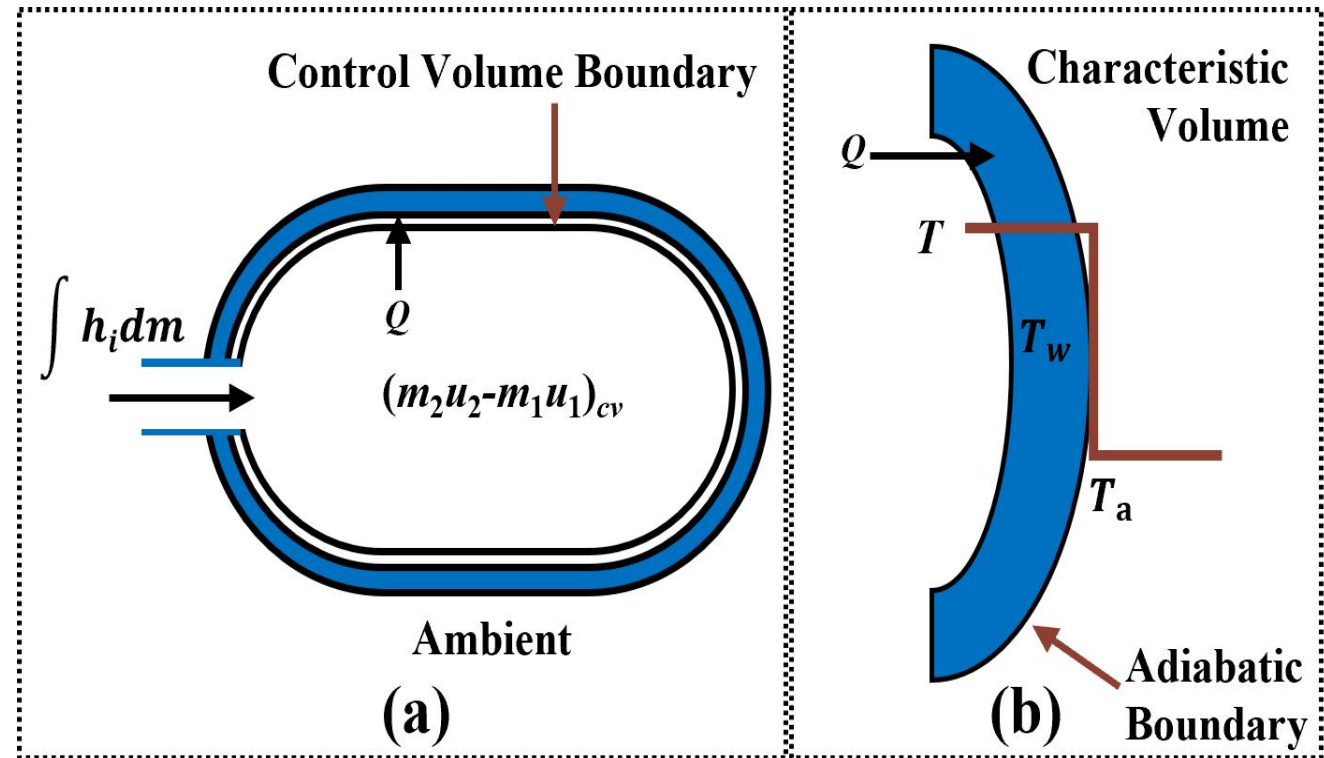
The original MC method assumes that: $T_{\text{final}} = T_{\text{wfinal}}$



$$T_{\text{final}} = \frac{m_{\text{final}}c_v T_{\text{adiabatic}} + MC T_{\text{initial}}}{MC + m_{\text{final}}c_v}$$



$$P_{\text{target}} = f(T_{\text{final}}, \text{SOC}_{\text{target}})$$



Improvements for MC method

Ending pressure determined by **dual-zone dual-temperature** model in modified MC method

Thermodynamic energy conservation during a refueling time of $t_{\text{initial}} - t_{\text{final}}$:

Hydrogen energy is transferred to the tank wall (assuming that the outer wall of the tank is **adiabatic**):

$$m_{\text{final}}c_v(T_{\text{adiabatic}} - T_{\text{final}}) = m_w c_w (T_{\text{wfinal}} - T_{\text{initial}})$$

+

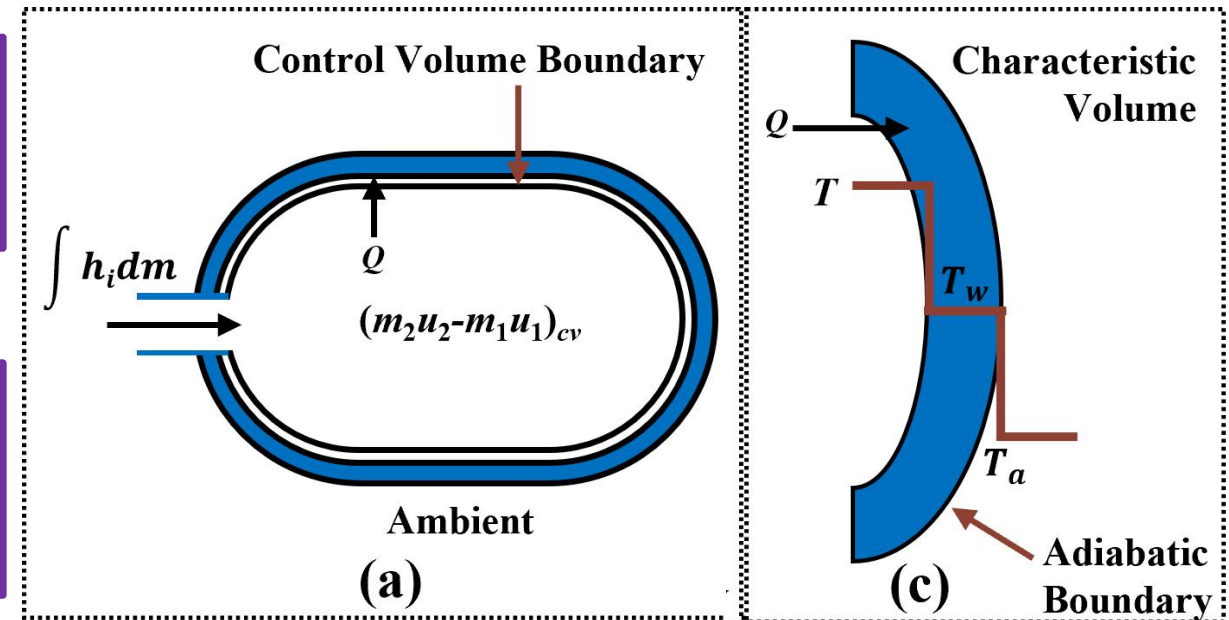
Heat transfer **energy balance**: Newton's Law of Cooling:

$$m_{\text{final}}c_v(T_{\text{adiabatic}} - T_{\text{final}}) = \int_{t_{\text{initial}}}^{t_{\text{final}}} A_{\text{in}} a_{\text{in}} (T - T_w) dt$$

+

Approximation of integration:

$$\int_{t_{\text{initial}}}^{t_{\text{final}}} A_{\text{in}} a_{\text{in}} (T - T_w) dt = k_1 A_{\text{in}} a_{\text{ave}} \int_{t_{\text{initial}}}^{t_{\text{final}}} (T - T_w) dt = k_1 k_2 a_{\text{ave}} A_{\text{in}} t_{\text{final}} (T_{\text{final}} - T_{\text{wfinal}}) = K A_{\text{in}} t_{\text{final}} (T_{\text{final}} - T_{\text{wfinal}})$$



Improvements for MC method

Ending pressure determined by dual-zone dual-temperature model in modified MC method

The **analytical solution for the final hydrogen temperature** is obtained solving the above equation.

$$T_{\text{final}} = \frac{m_{\text{final}}c_v T_{\text{adiabatic}} + m_w c_w T_{\text{initial}}}{m_{\text{final}}c_v} - \frac{(m_w c_w)^2 T_{\text{initial}} (m_{\text{final}}c_v + K A_{\text{in}} t_{\text{final}}) + K m_{\text{final}}c_v T_{\text{adiabatic}} m_w c_w A_{\text{in}} t_{\text{final}}}{(m_{\text{final}}c_v)^2 m_w c_w + K (m_{\text{final}}c_v)^2 A_{\text{in}} t_{\text{final}} + K m_{\text{final}}c_v m_w c_w A_{\text{in}} t_{\text{final}}}$$



Correction term in modified MC method

$$T_{\text{final}} = \frac{m_{\text{final}}c_v T_{\text{adiabatic}} + \mathbf{MCT}_{\text{initial}}}{\mathbf{MC} + m_{\text{final}}c_v}$$

Original MC method

Compare the analytical solutions of the final hydrogen temperature of the modified MC method and the original one:

In essence, the analytical solution of the final hydrogen temperature in the modified MC method **adds a correction term** due to the **distinction between hydrogen temperature and tank wall temperature**.

Improvements for MC method

Correction factors determined by simulation data from 0D1D model

- Calculate **capital K** from the above expressions.
- Substitute **average heat transfer coefficient** into capital K yields an equation for k .
- Use the **simulation data of the 0D1D model** fit the formula of k .
- A linear equation is obtained between k and **refuelling time**.
- Both the **slope D** and **intercept E** in the formula of k have a linear relationship with the **initial pressure**.

$$a_{ave} = \bar{a}_{in} = \frac{0.14\lambda \left(\frac{4}{\pi\mu}\right)^{0.67} \left(\frac{\bar{m}}{d_{in}}\right)^{0.67}}{D_{in}}$$

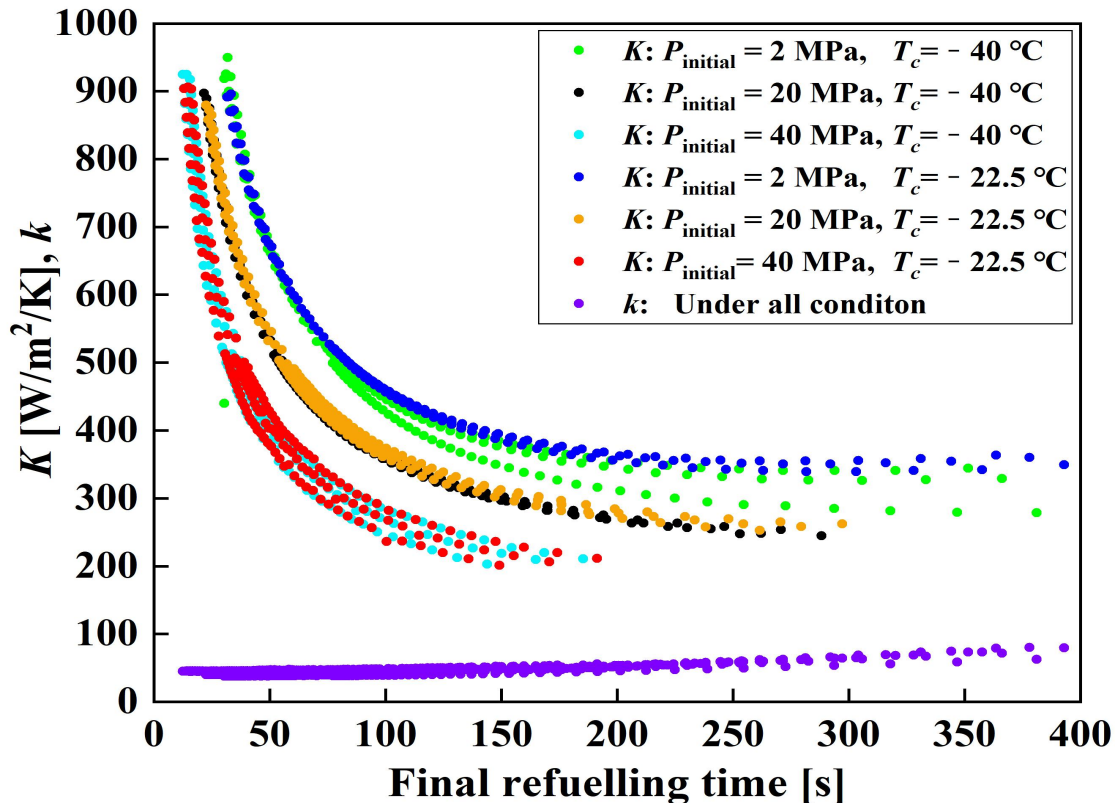
$$K = k_1 k_2 a_{ave} = \frac{m_{final} c_v (T_{adiabatic} - T_{final})}{A_{in} t_{final} (T_{final} - T_{wfinal})}$$

$$k = \frac{m_{final} c_v (T_{adiabatic} - T_{final})}{A_{in} t_{final} (T_{final} - T_{wfinal}) \left(\left(\frac{\bar{m}}{d_{in}}\right)^{0.67} / D_{in} \right)} = \frac{K}{\left(\left(\frac{\bar{m}}{d_{in}}\right)^{0.67} / D_{in} \right)}$$

$$k = D t_{final} + E$$

$$D = -0.0012 P_{initial} + 0.1013 \quad (R^2=0.997)$$

$$E = 0.2982 P_{initial} + 31.48 \quad (R^2=0.990)$$



Results and Discussion

Comparison for SOC results between the modified MC method and the original one

● The **modified final hydrogen temperature calculation method** is used instead of the original one to control the **ending pressure**. The control method of **refueling speed** still adopts that of **original MC method**. The simulations are conducted under a variety of initial and boundary conditions.

● Results show that the **final SOC** predicted by modified MC method is **more accurate** than that of the original one.

$$T_{\text{final}} = \frac{m_{\text{final}}c_v T_{\text{adiabatic}} + \text{MCT}_{\text{initial}}}{\text{MC} + m_{\text{final}}c_v}$$

$$\text{MC} = \text{AC} + \text{BC} \ln \left(\frac{U_{\text{adiabatic}}}{U_{\text{initial}}} \right)^{1/2} + \text{GC} (1 - e^{-\text{KC}\Delta t})^{\text{JC}}$$

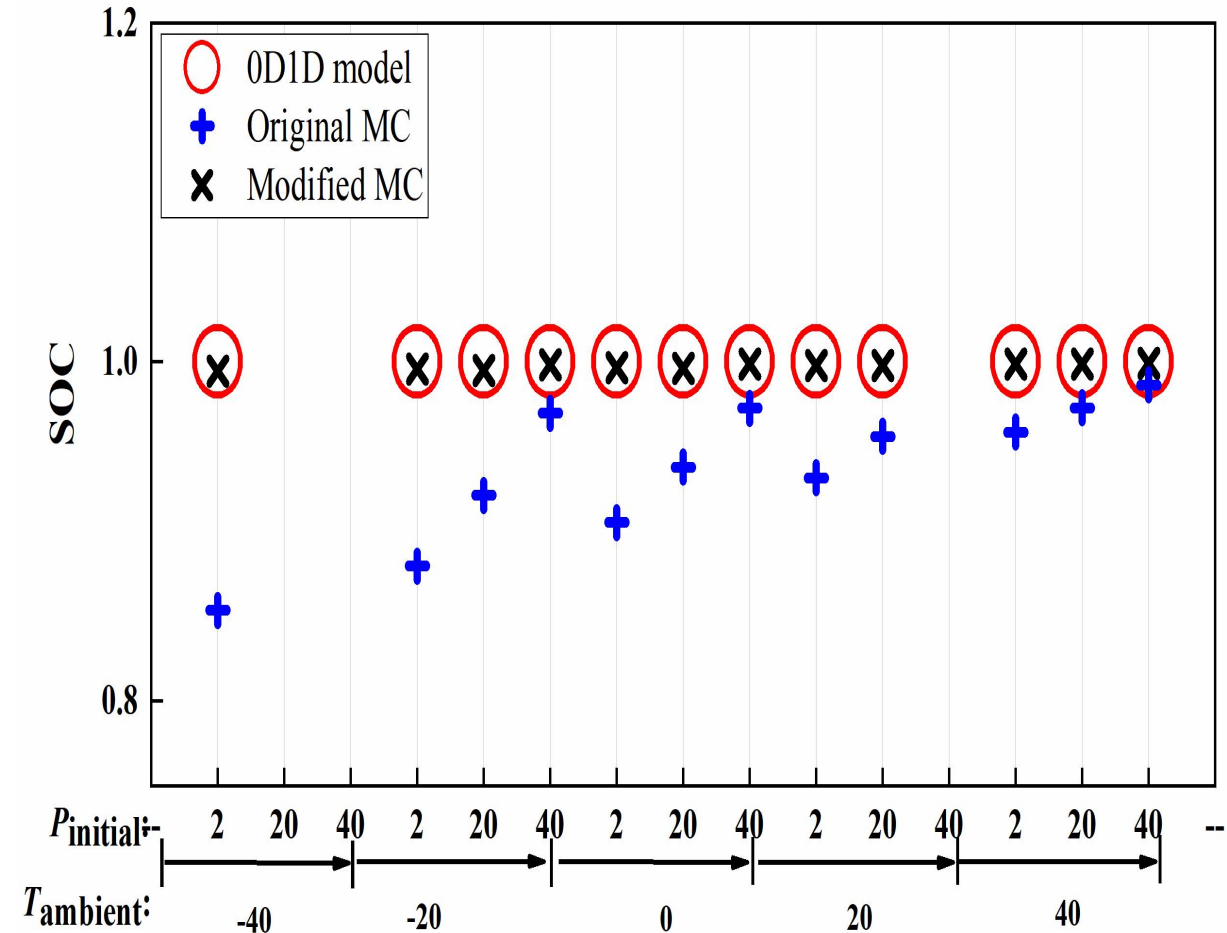
$$T_{\text{final}} = \frac{m_{\text{final}}c_v T_{\text{adiabatic}} + m_w c_w T_{\text{initial}}}{m_{\text{final}}c_v} - \frac{(m_w c_w)^2 T_{\text{initial}} (m_{\text{final}}c_v + K A_{\text{in}} t_{\text{final}}) + K m_{\text{final}}c_v T_{\text{adiabatic}} m_w c_w A_{\text{in}} t_{\text{final}}}{(m_{\text{final}}c_v)^2 m_w c_w + K (m_{\text{final}}c_v)^2 A_{\text{in}} t_{\text{final}} + K m_{\text{final}}c_v m_w c_w A_{\text{in}} t_{\text{final}}}$$

$$k = \frac{K}{\left(\left(\frac{\bar{m}}{d_{\text{in}}} \right)^{0.67} / D_{\text{in}} \right)}$$

$$k = D t_{\text{final}} + E$$

$$D = -0.0012 P_{\text{initial}} + 0.1013 \quad (R^2=0.997)$$

$$E = 0.2982 P_{\text{initial}} + 31.48 \quad (R^2=0.990)$$



Conclusions

● For a complete hydrogen filling process, the **total amount of heat transferred by convection** between hydrogen and the inner wall of the storage tank can be expressed as an equation of the **final hydrogen temperature, final wall temperature, final refueling time, tank inner surface area and correction factor**.

● The correction factor k can be expressed as a **linear function with final filling time**. Both the **slope D** and **intercept E** in correction factor k have a linear function with **initial pressure**.

$k = Dt_{\text{final}} + E$, where $D = -0.0012P_{\text{initial}} + 0.1013$ ($R^2=0.997$), $E = 0.2982P_{\text{initial}} + 31.48$ ($R^2=0.990$).

● The **modified final hydrogen temperature** calculation method is used to replace the original one to control the **ending pressure**. The control method of **refueling speed** still adopts that of **original MC method**. Simulation results show that the **final SOC** predicted by modified MC method is **more accurate** than that of the original one.

● **Accurate estimation for final hydrogen temperature, ending pressure and final SOC is important** for improving hydrogen refuelling protocol and ensuring hydrogen refuelling **safety**.

Thanks for your attentions!

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